

```
> restart:with(plots):
```

```
Warning, the name changecoords has been redefined
```

Differenciálegyenlet $(\Delta - a^2) \Phi(x, y, z) = -4 \pi \rho; \rho = \frac{e^{(-r)}}{8 \pi}$

Gömbszimmetrikus megoldásra $\phi(r) = r \Phi(r), \left(\frac{\partial^2}{\partial r^2} \phi \right) - a^2 \phi = -4 \pi r \rho, \phi(0) = 0, \phi(\infty) = 0$

Diszkretizálva $\phi_{i+1} - (2 + a^2 \delta^2) \phi_i + \phi_{i-1} = -\frac{\delta^2 (r e^{(-r)})_i}{2}$

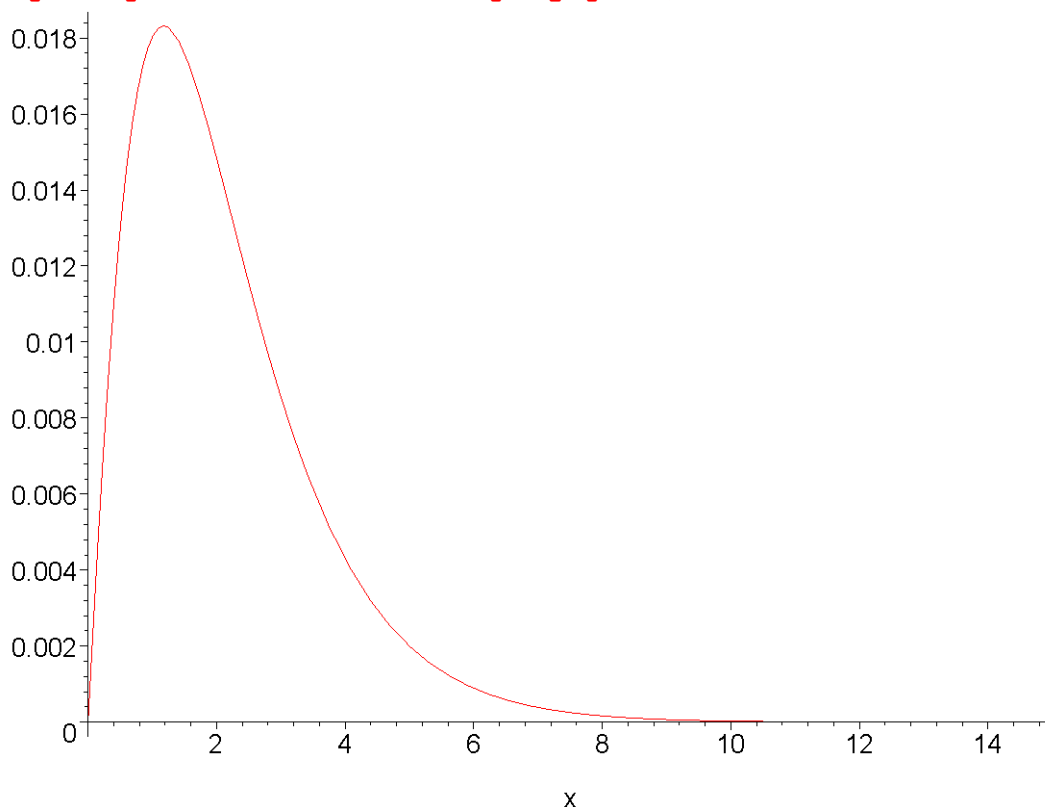
Az egzakt megoldás $\phi := r \rightarrow \frac{e^{(-ar)} - e^{(-r)} \left(1 + \frac{br}{2} \right)}{b^2}; b := 1 - a^2$

```
> simplify( ( ( ( \frac{\partial^2}{\partial r^2} \phi(r) ) - a^2 \phi(r) + \frac{r e^{(-r)}}{2} ) ) )
```

0

```
> a:=3.:mx:=5*a:
```

```
p1:=plot(phi(x), x=0..mx):display(p1);
```



A numerikus megoldás a tridiagonális egyenletrendszer előre-hátra helyettesítésével

```
mx := 15.; n := 160; delta := \frac{mx}{n + 1}
```

```
delta := .09316770186
```

A tridiagonális mátrix elkészítése

$\alpha := 1.; \beta := -(2 + \delta^2 a^2); \text{gama} := 1.; \text{for } i \text{ to } n \text{ do } x_i := i \delta; d_i := -\frac{\delta^2 x_i e^{(-x_i)}}{2} \text{ end do}$

Hátra helyettesítés

$$g_{n-1} := -\frac{\alpha}{\beta};$$

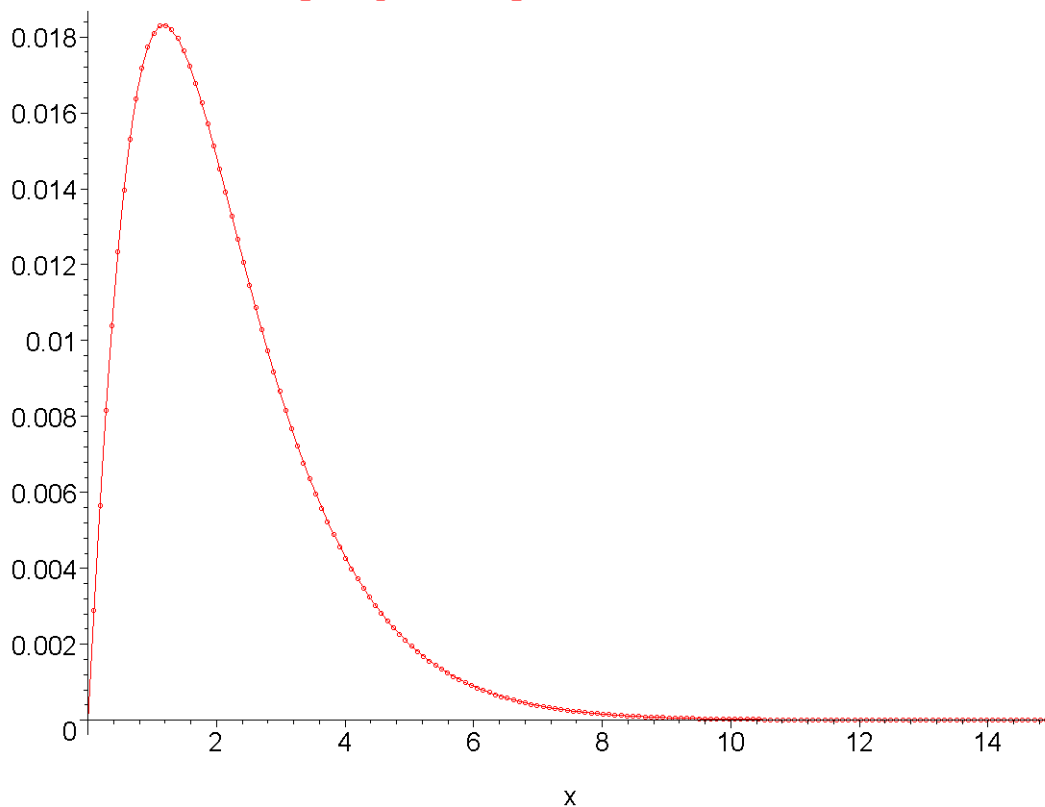
$$h_{n-1} := \frac{d_n}{\beta};$$

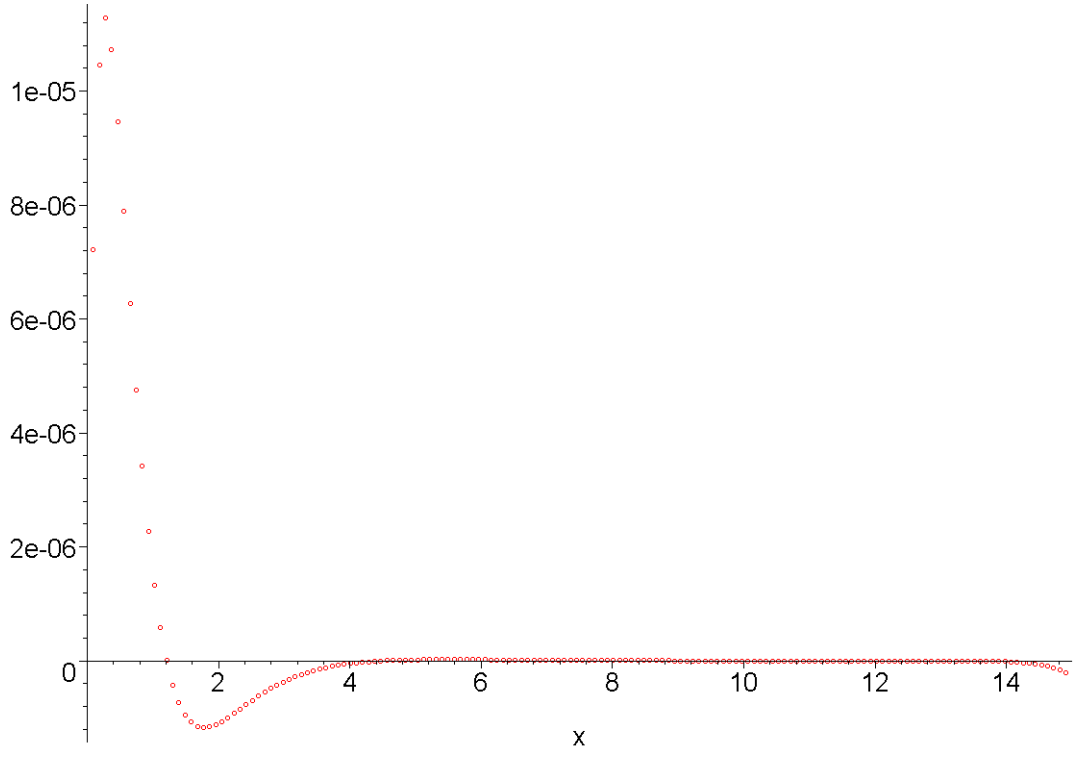
$\text{for } i \text{ from } n-1 \text{ by } -1 \text{ to } 2 \text{ do } g_{i-1} := -\frac{\alpha}{\beta + \text{gama } g_i}; h_{i-1} := \frac{d_i - \text{gama } h_i}{\beta + \text{gama } g_i} \text{ end do}$

Előre helyettesítés

$\psi_1 := \frac{d_1 - \text{gama } h_1}{\beta + \text{gama } g_1}; \text{for } i \text{ to } n-1 \text{ do } \psi_{i+1} := g_i \psi_i + h_i \text{ end do}$

```
> p1:=plot(phi(x), x=0..mx):
  l := [[ x[k], psi[k]] $k=1..n]:
  p2:=plot(l, x=0..mx, style=point, symbol=circle):
> display({p1,p2});
> l := [[ x[k], psi[k]-phi(x[k])] $k=1..n]:
  plot(l, x=0..mx, style=point, symbol=circle);
```





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